

## Features

### CAR 2 CAR Communication Consortium



#### About the C2C-CC

Enhancing road safety and traffic efficiency by means of Cooperative Intelligent Transport Systems and Services (C-ITS) is the dedicated goal of the CAR 2 CAR Communication Consortium. The industrial driven, non-commercial association was founded in 2002 by vehicle manufacturers affiliated with the idea of cooperative road traffic based on Vehicle-to-Vehicle Communications (V2V) and supported by Vehicle-to-Infrastructure Communications (V2I). Today, the Consortium comprises 61 members, with 11 vehicle manufacturers, 31 equipment suppliers and 29 research organisations.

Over the years, the CAR 2 CAR Communication Consortium has evolved to be one of the key players in preparing the initial deployment of C-ITS in Europe and the subsequent innovation phases. CAR 2 CAR members focus on wireless V2V communication applications based on ITS-G5 and concentrate all efforts on creating standards to ensure the interoperability of cooperative systems, spanning all vehicle classes across borders and brands. As a key contributor, the CAR 2 CAR Communication Consortium works in close cooperation with the European and international standardisation organisations such as ETSI and CEN.

#### Disclaimer

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## Document information

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**Table 1: Document information**

**Changes since last version**

<b>Title:</b>	<b>Features</b>		
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**Table 2: Changes since last version**

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## 1 Introduction

### Other (informational)

RS\_FEA\_147

Within the open system architecture of Cooperative Intelligent Transport System (C-ITS) four types of participants, called sub-systems, are identified in [EN 302 665]: vehicle, roadside, personal, and central. Each of these sub-systems includes an ITS-S, but based on their sub-system specific equipment they enable different features. As a result of their feature list and their role in traffic, for each sub-system a set of use cases becomes possible to improve road safety and traffic efficiency.

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## 2 Scope

### Other (informational)

**RS\_FEA\_146**

The present document provides all features in scope of a vehicle sub-system from C2C-CC point of view. This set of features is the consolidated and communicated understanding of the core vehicle system features in a C2C-CC Basic System. According to the C2C-CC contract, the present list focuses on specifying the C2C-CC Basic System on the vehicle ITS station transmitting side. Moreover, this set is oriented towards enabling the vehicle use cases as included in the current C2C-CC release. Details about the content of the release can be found in [C2CCC RelOv] and are listed in brief in the following:

- emergency vehicle warning
- dangerous situation
- stationary vehicle warning
- traffic jam ahead warning
- collision risk (exchange of IRCs)
- adverse weather conditions

The use cases as part of the current C2C-CC release do not constitute a mandatory set of applications to be implemented as part of a C2C-CC basic system. Only a subset of them might be supported by a specific implementation of the C2C-CC Basic System.

In terms of C2C-CC a feature defines a service or a major part of the C2C-CC Basic System. They always detail an objective, but – like objectives – without any further specification about its details. As a result, features are not directly testable.

Features itself are detailed by one or more requirements. A feature can be assumed as tested, if all requirements, which detail this feature, are tested.

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## 3 Conventions used

### Other (informational)

RS\_FEA\_152

Conventions used in this and other C2C-CC specification documents can be found in [C2CCC ConV].

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## 4 Definitions

### Definition

RS\_FEA\_149

A *C2C-CC Basic System* is a C-ITS vehicle sub-system as outlined in this document.

### Definition

RS\_FEA\_427

'*Vehicle states*' comprise absolute position, heading and speed at a certain point in time.

### Definition

RS\_FEA\_428

Information provided with a '*confidence level*' of 95 % means that the true value is inside the confidence interval for at least 95 % of the data points in a given statistical base.



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## 5 Feature specification

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**Feature** **RS\_FEA\_176**

AT changeovers shall be triggered in such a manner that at least 95 % of all trips are divided into three segments: A start segment in the beginning of a trip, an end segment and a middle segment in between.

Details:

Detailed by:

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**Feature** **RS\_FEA\_405**

The C2C-CC Basic System shall support services for confidentiality within the communication with the PKI entities.

Details:

Detailed by:

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**Feature** **RS\_FEA\_189**

The vehicle state estimation (see RS\_FEA\_427) shall include confidence intervals for the defined confidence level of 95% according to the definition in RS\_FEA\_428, as a standardized description of the estimation accuracy.

Details:

Detailed by:

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**Feature** **RS\_FEA\_430**

The C2C-CC Basic System shall provide services for communicating with other ITS-S by using ITS-G5, operating in the frequency band 5855 MHz to 5925 MHz.

Details:

Detailed by:

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**Feature** **RS\_FEA\_431**

The C2C-CC Basic System shall provide services to avoid channel congestion of the shared media.

Details:

Detailed by:

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**Feature** **RS\_FEA\_432**

The C2C-CC Basic System shall provide mitigation techniques to avoid disturbing other services operating at nearby frequencies (i.e. CEN DSRC).

Details:

Detailed by:

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**Feature** **RS\_FEA\_433**

The C2C-CC Basic System shall provide services for transmitting, receiving and forwarding messages to multiple, geographically scattered and movable entities.

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Details:

Detailed by:

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**Feature**

**RS\_FEA\_434**

The C2C-CC Basic System shall provide services for handling multiple messages of different types on the sender side.

Details:

Detailed by:

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**Feature**

**RS\_FEA\_435**

The C2C-CC Basic System shall provide services for regularly transmitting information about itself and receiving of those information from other ITS-S in its vicinity.

Details:

Detailed by:

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**Feature**

**RS\_FEA\_436**

The C2C-CC Basic System shall provide services for transmitting information about events on demand and receiving of those events from other ITS-S.

Details:

Detailed by:

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**Feature**

**RS\_FEA\_437**

The C2C-CC Basic System shall use a standardized message format for each message type it exchanges with other ITS-S.

Details:

Detailed by:

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**Feature**

**RS\_FEA\_438**

The C2C-CC Basic System shall check relevant host vehicle dynamics data (e.g. position, speed, heading, longitudinal acceleration, yaw rate) for plausibility.

Details:

Detailed by: RS\_BSP\_431, RS\_BSP\_514

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**Feature**

**RS\_FEA\_439**

The C2C-CC Basic System shall use certificates (Authorization Tickets) and signatures to ensure authentication of message originator.

Details:

Detailed by: RS\_BSP\_160

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